

Agent-Based Participatory Simulation Activities for the Emergence of Complex Social Behaviors

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Background

Social organizations shows different levels of abstraction:

1. **macro-level** : complex self-organizing systems
2. **micro-level** : behaviour of individuals

A **M**ulti **A**gent **S**ystem can be employed in order to describe self-organizing systems:

1. To **mimic** real societies by implementing artificial societies
2. To create a **quasi-experimental observation-generation** environment

Taxonomy

Two types of agents (Stone and Veloso 2000):



Homogeneous



Heterogeneous

Two kinds of configurations:

- Not communicating
- **Communicating**

Two ways of acting:

- **Reactive**
- **Deliberative**

Traditional approach

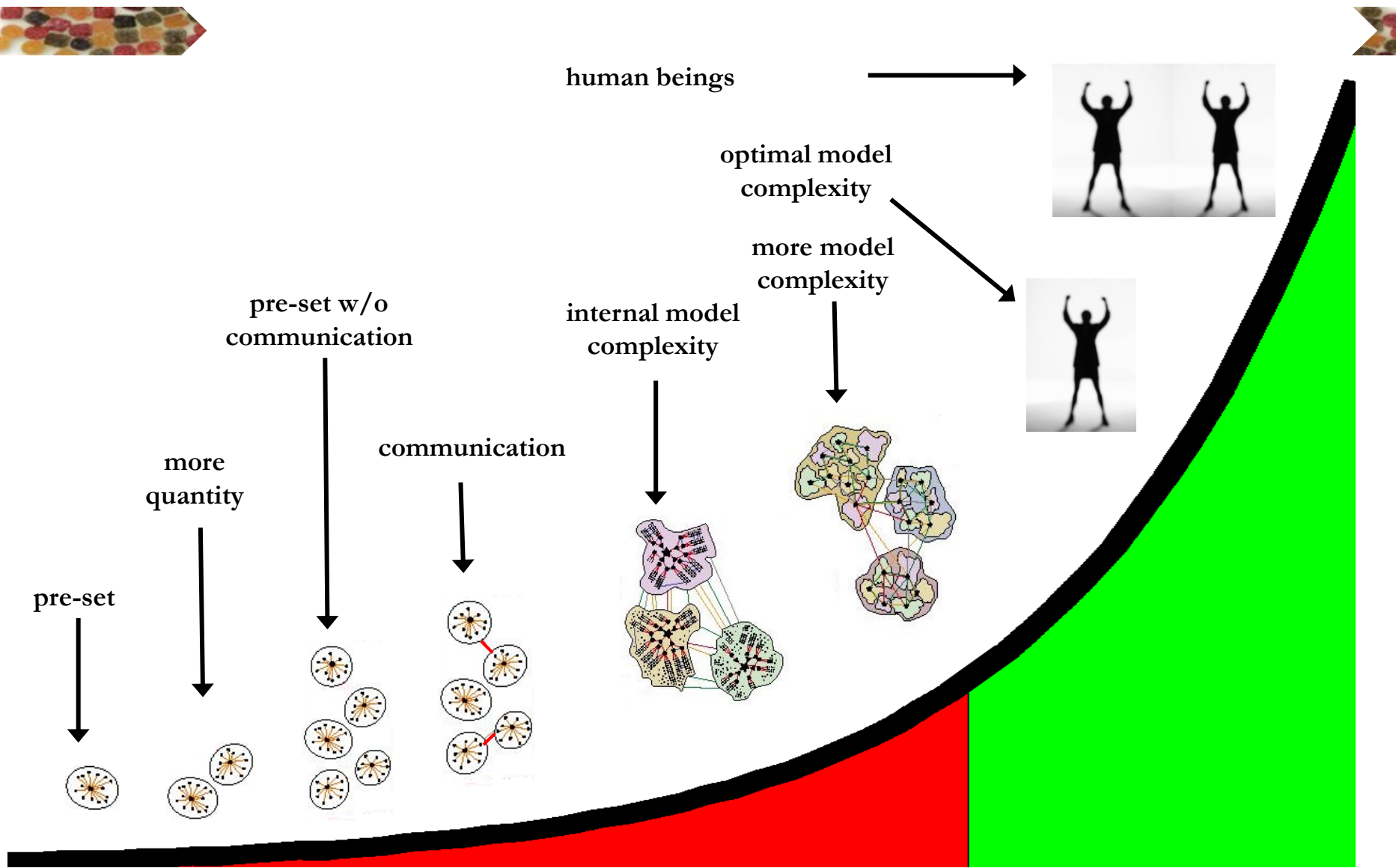
Accurate simulations require:

Heterogeneous, Communicative and Deliberative agents.

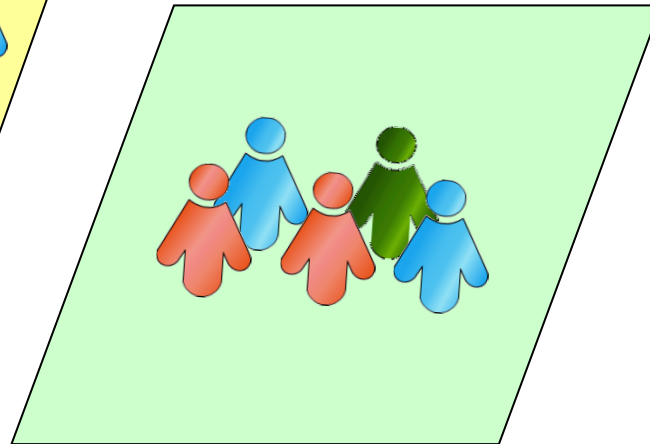
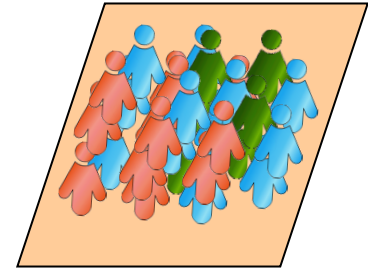
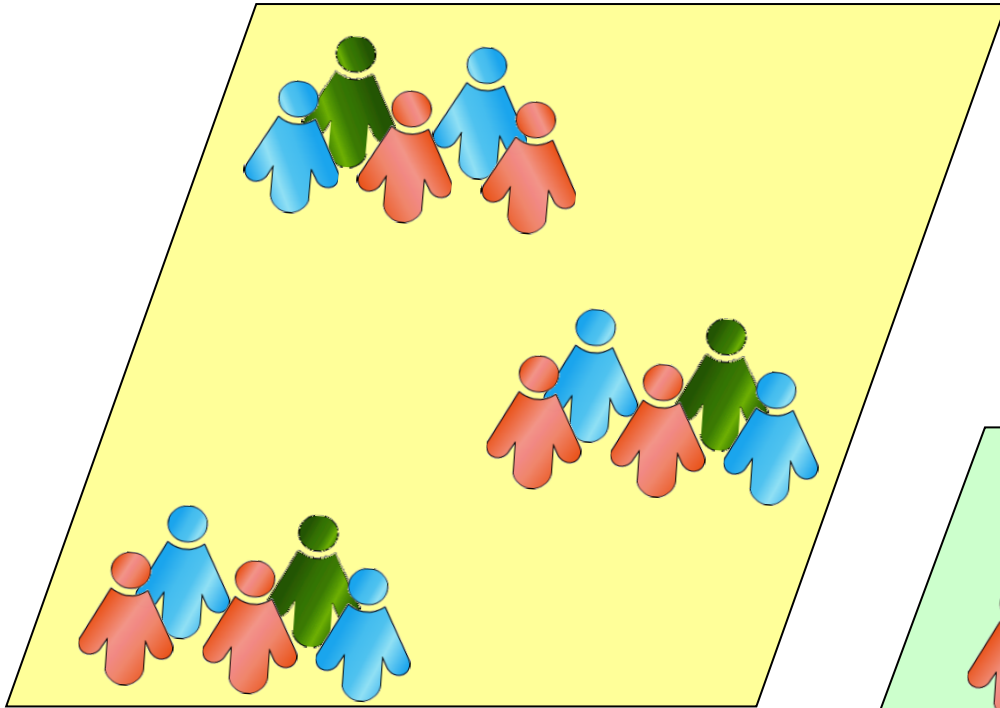
The historical approach suggests:

- to increase the **model complexity**
- to scale up the **number of agents**
- to improve the **behavior of agent**

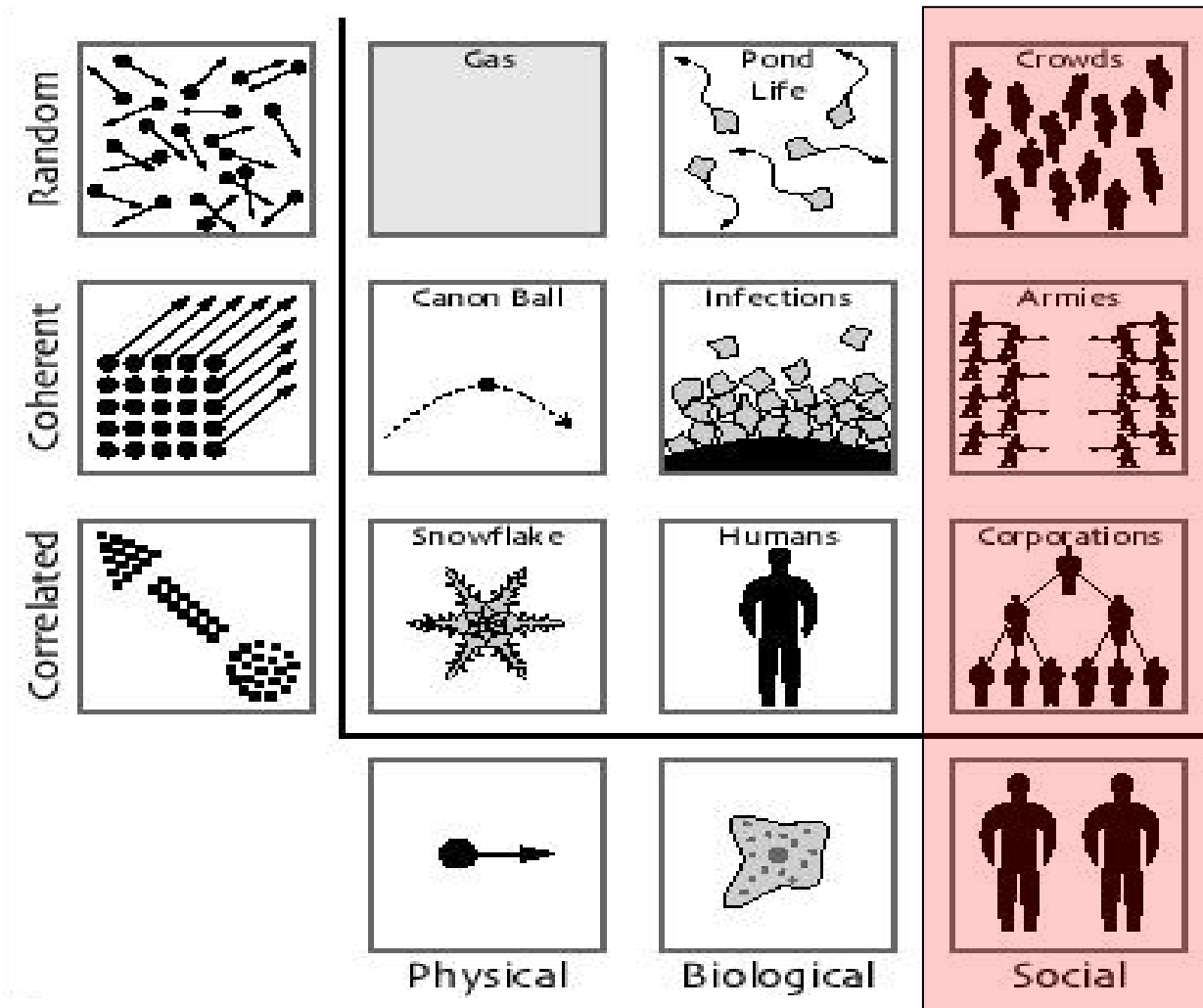
Complexity



Number



Behavior



Main question

Are we sure that is the
best approach to make
accurate simulations

?

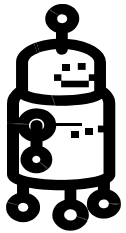
Participatory Simulation

Participatory **S**imulation represents an alternative approach that expands the capability of interactions at **run time**

- Each user can play the role of individual system entities and can see how the behaviour of the system as a whole can emerge from it participation
- PS promotes the interaction among agents controlled by pre-fixed behavioural models and driven by humans

Complex social behaviour

To promote the **emergence of complex social behaviour** we propose to exploit the PS to play games in which:



Each agent can be controlled by a **software** that implements hand-made behavioural model

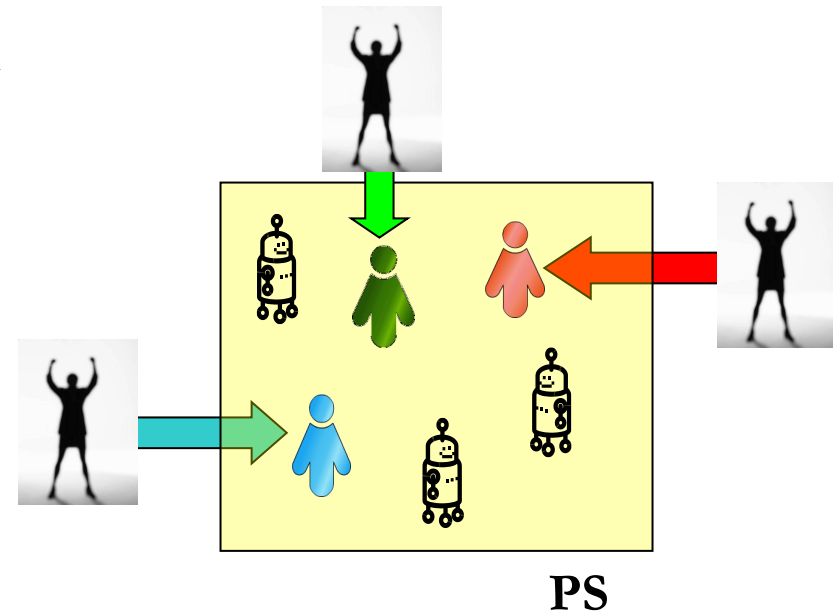


Each **human being** is represented in the game by his digital avatar that can be fully controlled



Framework for PS

Participatory **F**ramework supports the management of the interaction between humans and their agents into any PS

- A user can participate in the evolution of the (remote) simulated complex system by means of PF
- PF handles a connection between a user and a **remote agent** by implementing a session level over a TCP stack
- The user drives a specific agent by means of a client at application level that communicates over a network connection to the synthetic environment



Speed of PS evolution



The participation of multiple users can slow down the evolution of the simulated complex system to unacceptable speed depending on:

- a **momentary interruption** due to congestions or outages of the network communications,
- a **permanent interruption** due to the client or server disconnection and
- a **low level of reactivity** due to the lack of attention from user.

Today frameworks for PS

Open issues:

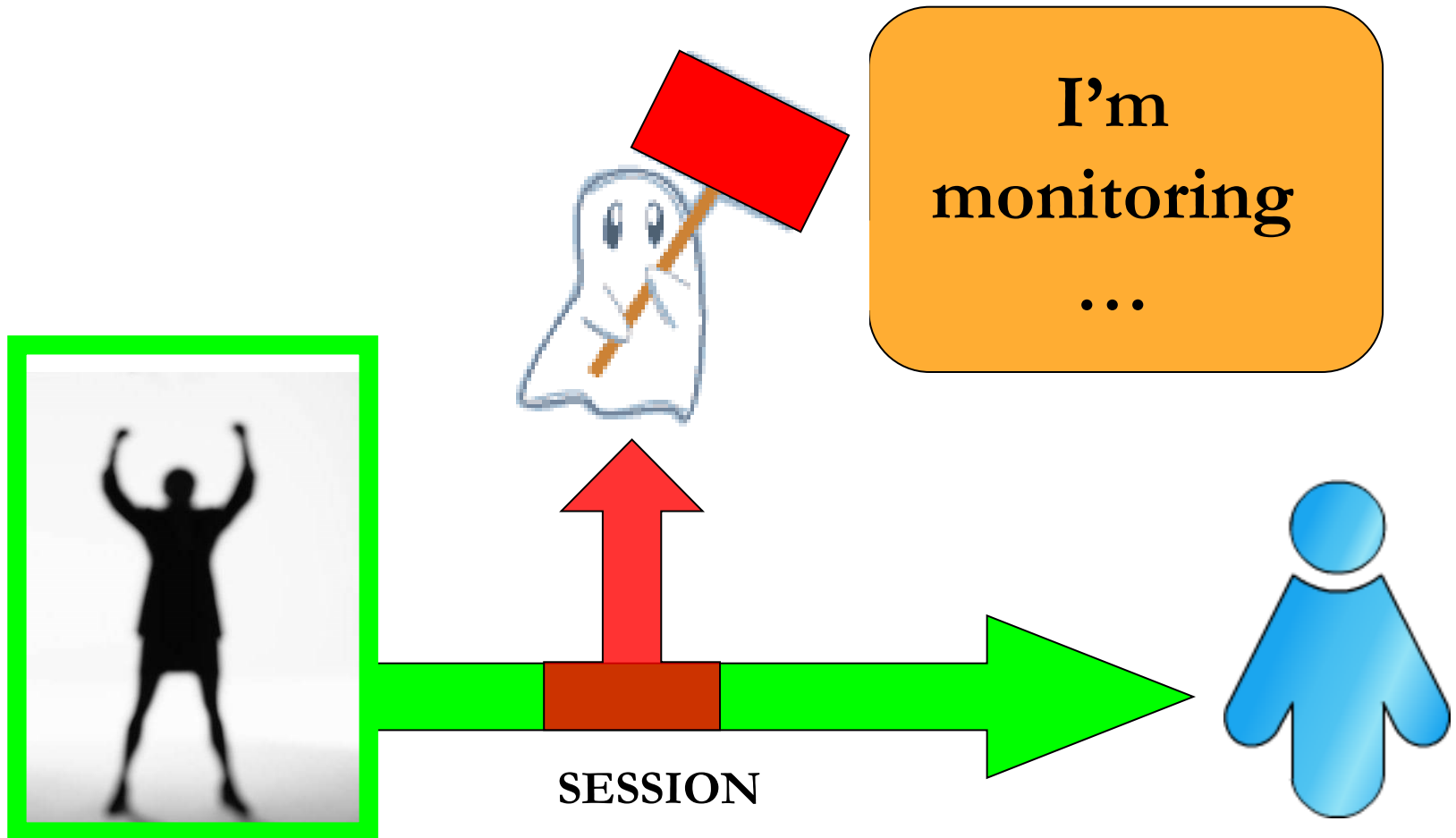
1. the **responsiveness** is not guaranteed
2. the lost connections **can not be resumed**
3. the agent's behaviour is **prefixed**

Goal of PF

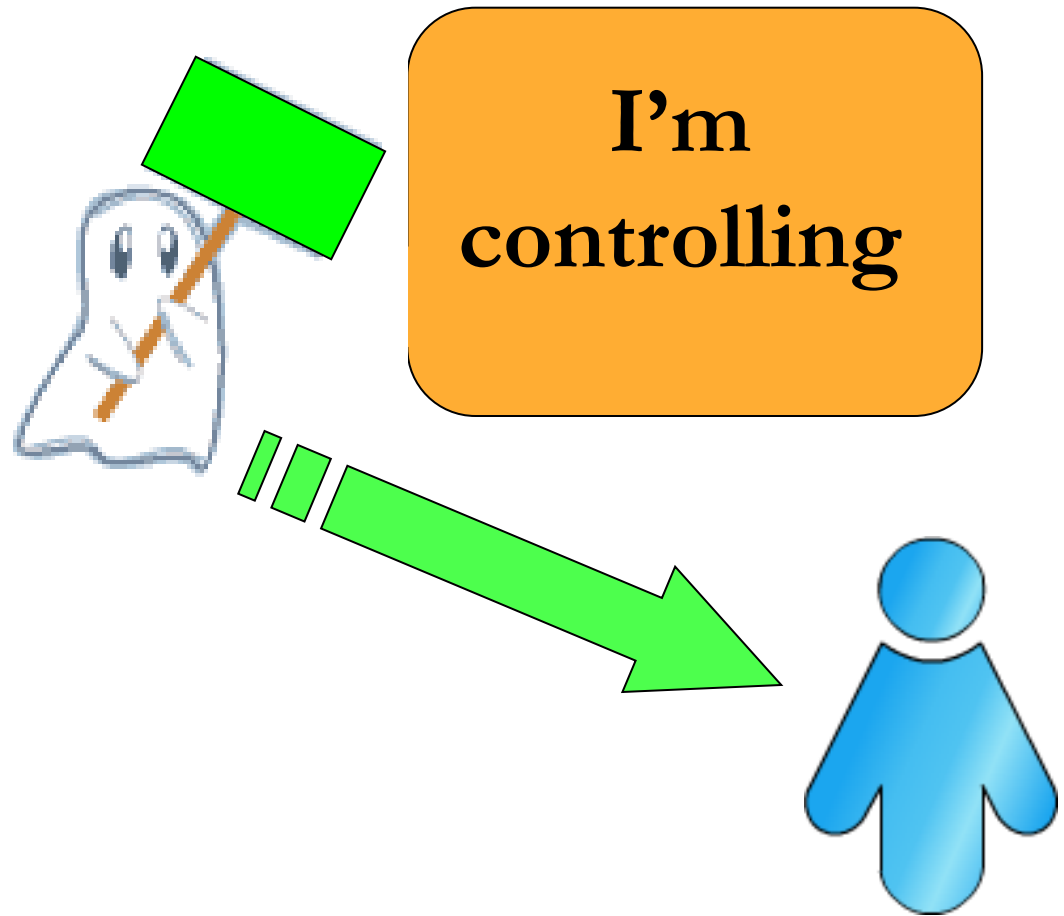
To maintain the speed of the system evolution over a certain threshold by supporting the human playability

- If a human player is not able to participate in all the turns on time, PF guarantees the correctness of the sequence serialization by imposing to the slow agents to be played by their ghost mimic players
- PF implements a **session recovery** mechanism that allows users to control their agents once again, after the interruption of the network communications

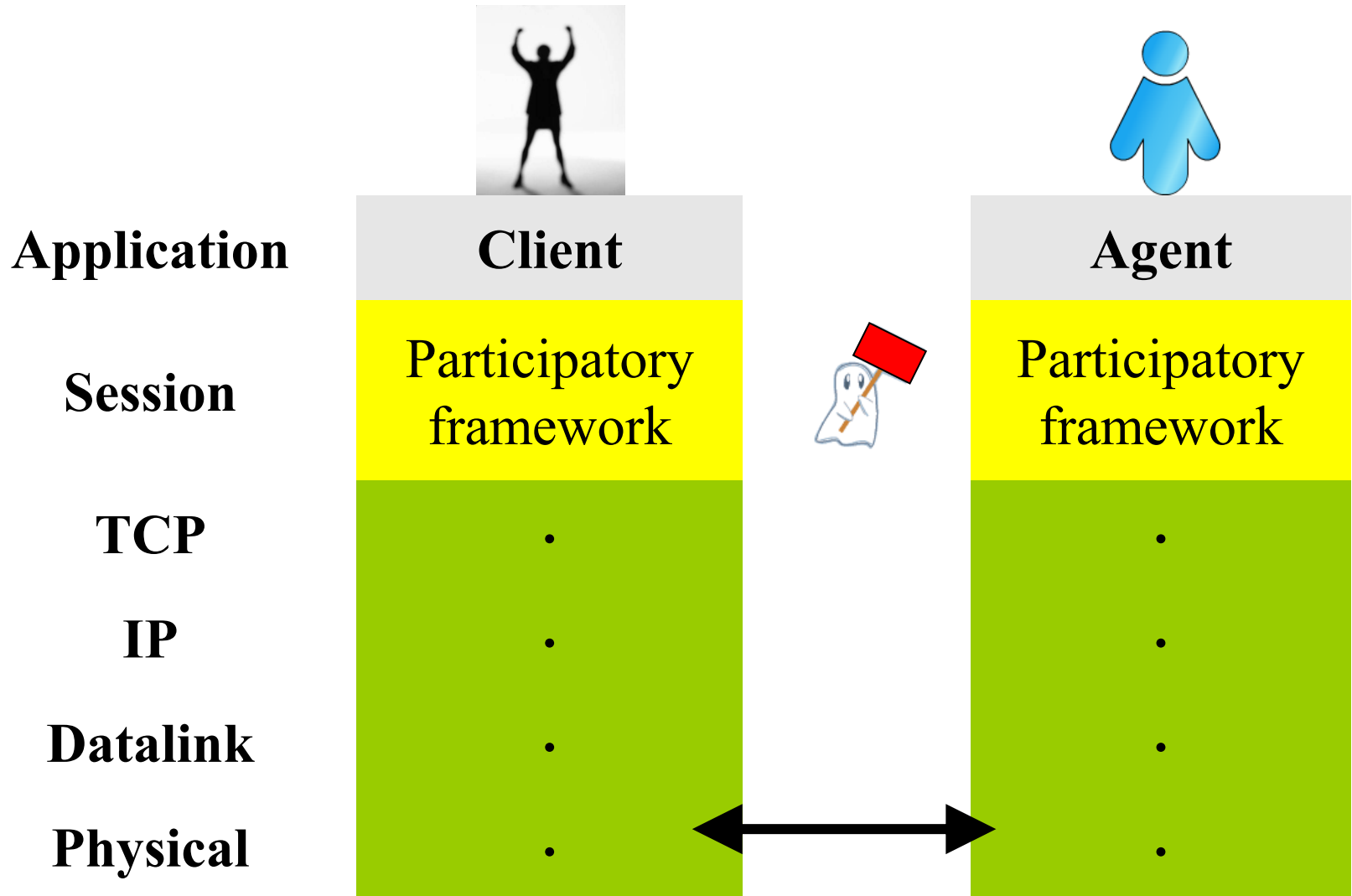
Ghost player



Ghost player in action



Network implementation of PF



Communication Management

The CM mechanism of the ghost player consists of:

- The **Action Timeout Handler (ATH)** avoids that a user low reactivity slows down the evolution of the entire systems
- The **TCP Timeout Handler** decides if the connection between an agent and a client is closed, based on statistical calculations related to the previous performance according to the agent responsiveness on client side and user responsiveness on agent side

Action Timeout Handler

ATH controls the responsiveness of the client (at agent side). ATH monitors the time to receive a new action



If action timeout does not expires before the response from the client, the agent will execute user actions



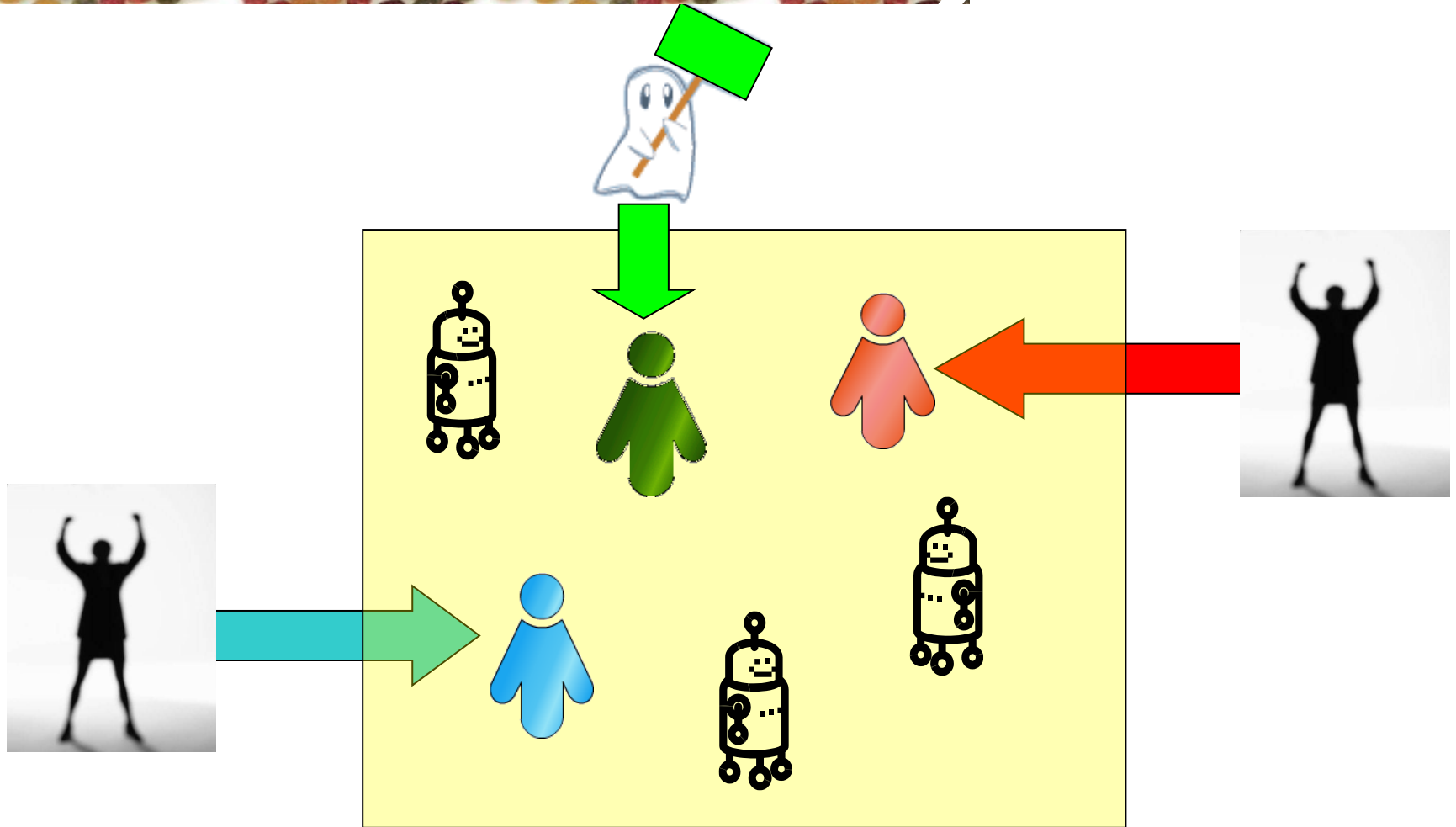
Else, the ghost mimic player drives the agent in place of the human being making 1 move

TCP Timeout Handler



- **From the agent side**, TCP TH sets the state of the connection as **“broken”**, when a maximum number of consecutive action timeout occurs
- **From the client side**, TCP TH sets the state of the connection as **“broken”**, only after an amount of time (called TCP timeout) has passed without receiving any session ack from the agent

PF with Ghost player



Mimicking capabilities



Which move should the Ghost player choose?

- Random model
- Prefixed behavioural model
- Adaptive behavioural model
- **Mimic** model

The Ghost player tries to mimic human player's strategy

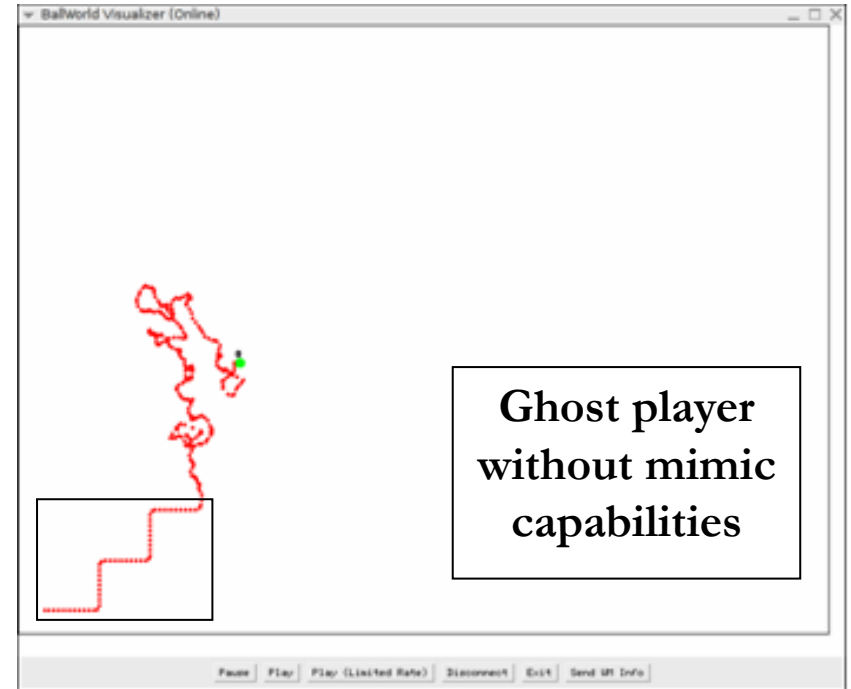
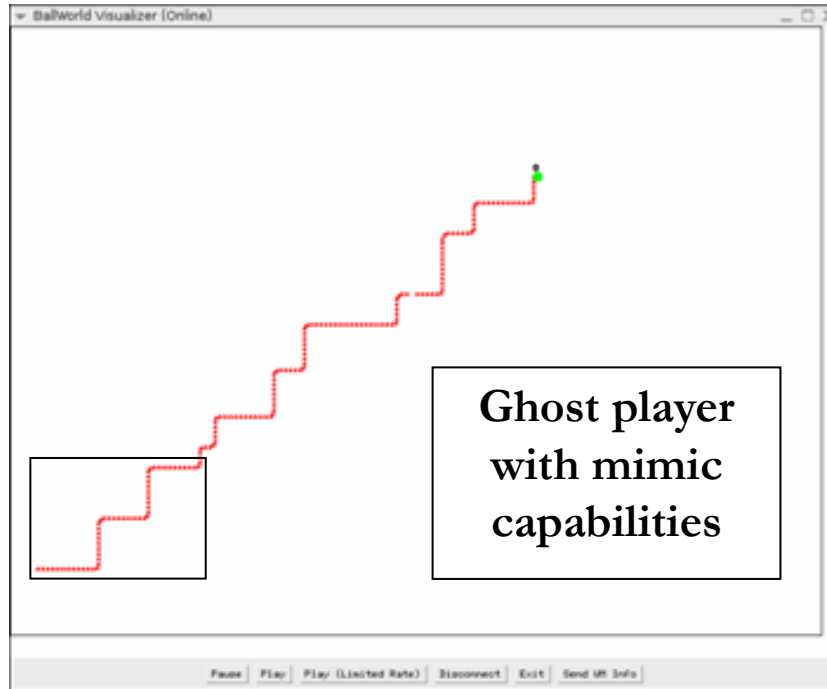
Preliminary results

We develop a predator-prey artificial ecosystem
(**pursuit domain**)

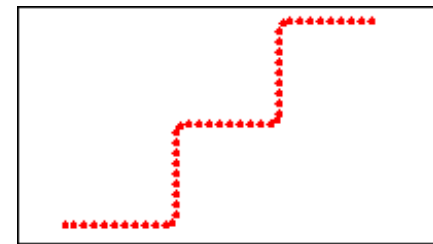
- The prey goal is to run away, while the predator one is to pursue the prey ●
- Once a predator reaches a prey, it kills it. Otherwise, if a long period passes, predator dies for starvation

In these preliminary tests, we focus on the **escape trajectory** of the prey-agent ●●●●●●●●

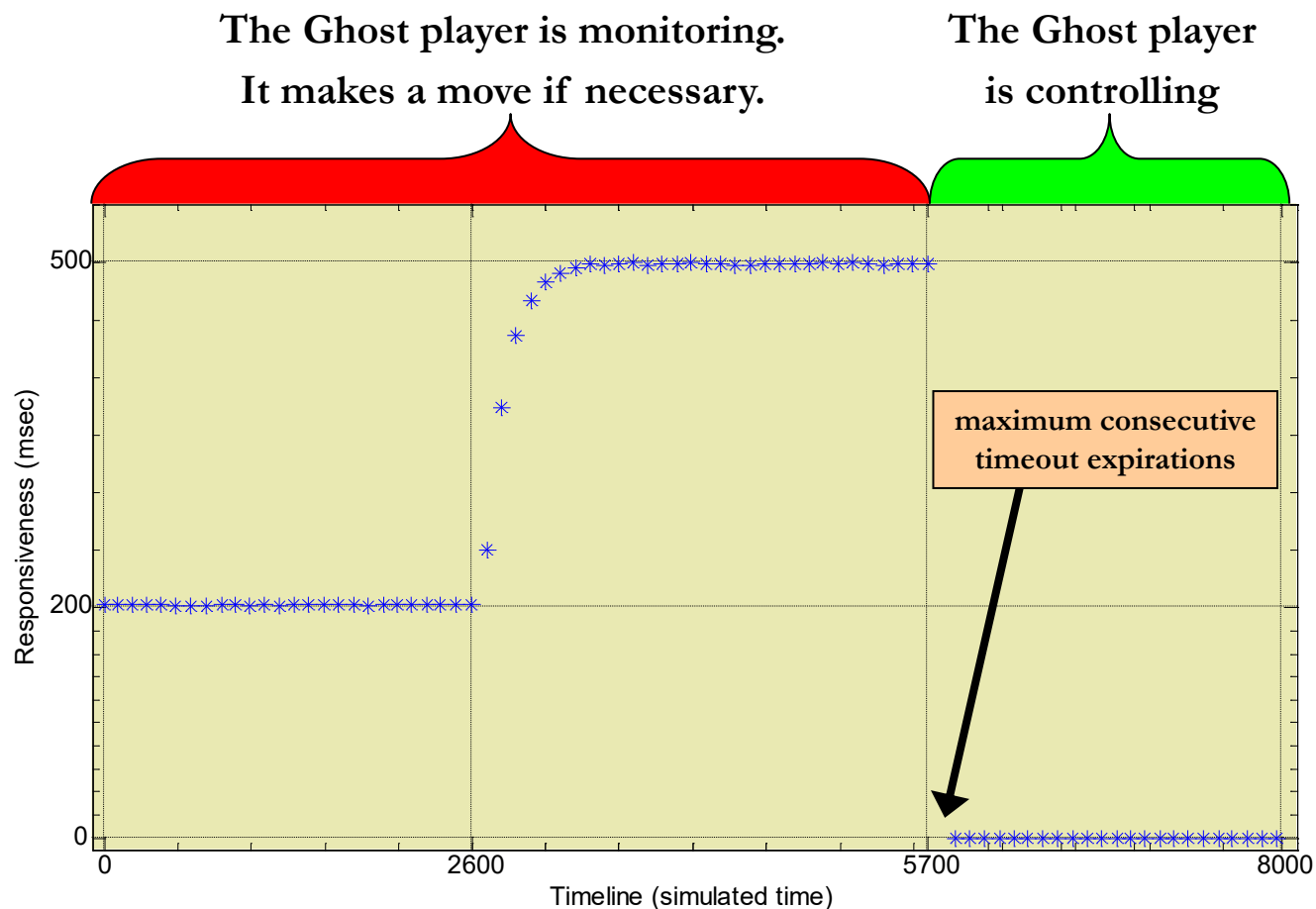
Visualization of escape trajectory



The **pattern of moves** related to the human being is similar to a stairway



Plot of responsiveness



agent is driven by
remote human player

action timeout
expirations

agent is driven by
Ghost player

Towards a new Turing Test



Can we construct an agent so that no human being can **recognize it as a software** while playing with it for a long time

?

If this **mimic game** is successful, we could safely assert that this software has passed a new version of the Turing test (Turing, 1950)

Conclusions



- This prototype supports the participants with an **endless session level** that allows the human player to disconnect from the synthetic environment while a ghost player takes the control of his agent
- A **mimicking strategy** has been proposed to drive the ghost player
- Preliminary results confirmed the **efficacy** of our approach

Future works



- We are designing our software prototype to pass to a **new version** of the **Turing test** using some methodologies gathered from the field of Machine Learning
- We are planning a **massive experimental campaign** to study the performance of our PF
- These trained behavioral models may be very effective in digital cinema, edutainment, and multiplayer games

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